

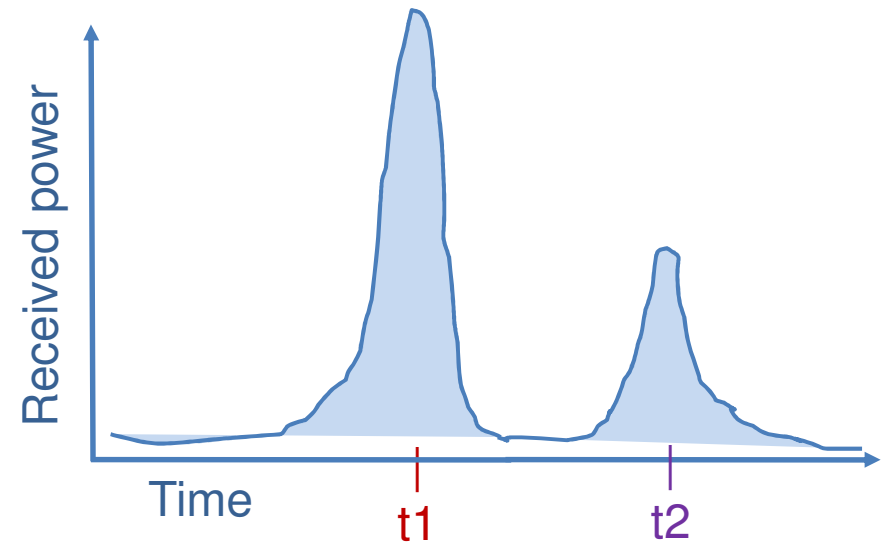
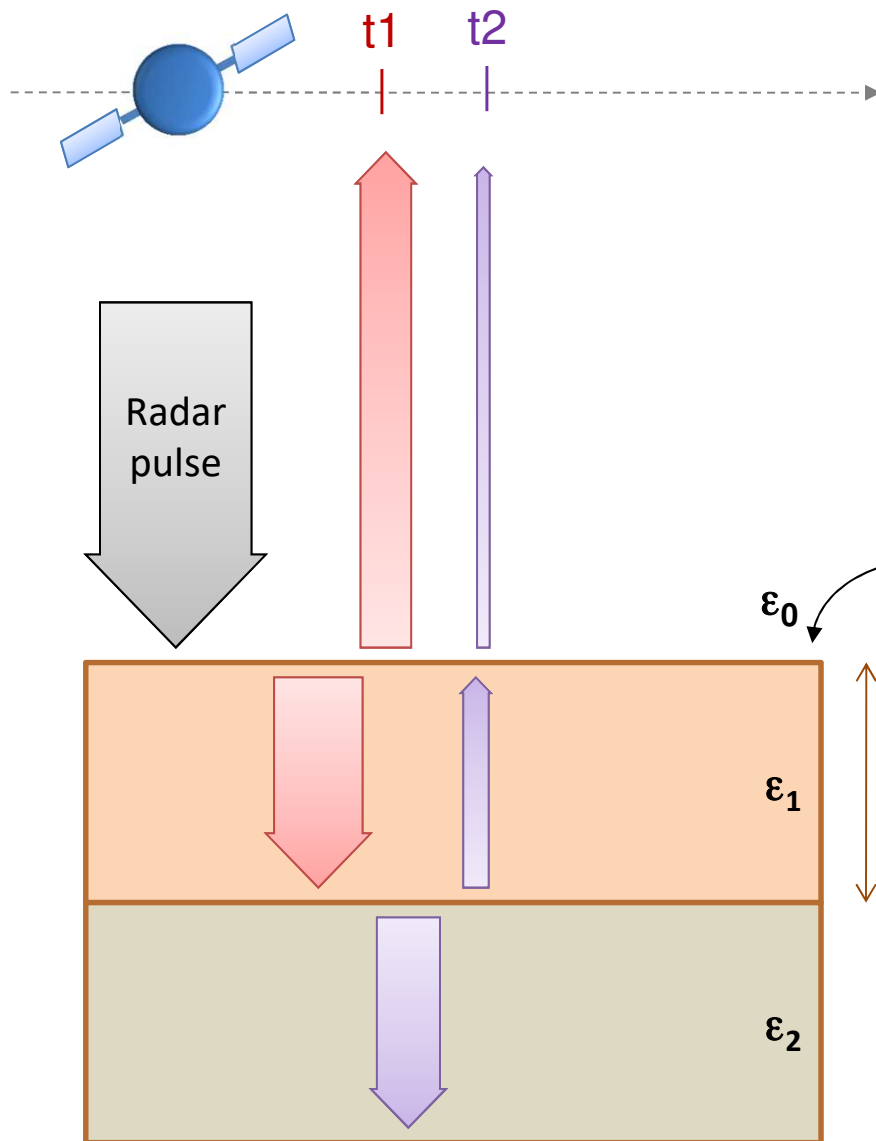
**Medium and long-term perspectives of  
radio sounding & radar instrumentation techniques  
for the study of the  
surfaces & subsurfaces of solar system objects**

Alain Herique, Wlodek Kofman, Sonia Zine  
IPAG – Université Grenoble Alpes

# Outline

1. How do radars work?
2. A few examples & results
3. Perspectives

# How do radars work?



$\epsilon_0$

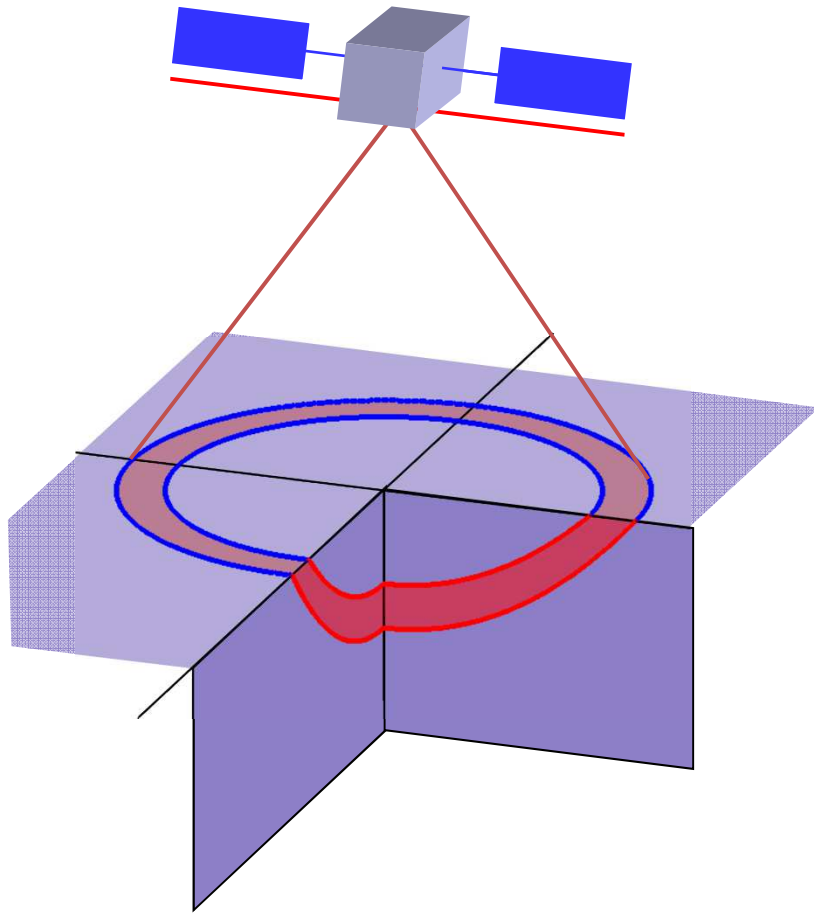
Reflection :  $\propto (\sqrt{\epsilon_a} - \sqrt{\epsilon_b}) / (\sqrt{\epsilon_a} + \sqrt{\epsilon_b})$

Propagation :  $h = (t \cdot c) / (2 \sqrt{\epsilon})$

And also...

- ... scattering and absorption in the medium
- ... scattering at interfaces (sensitive to roughness)

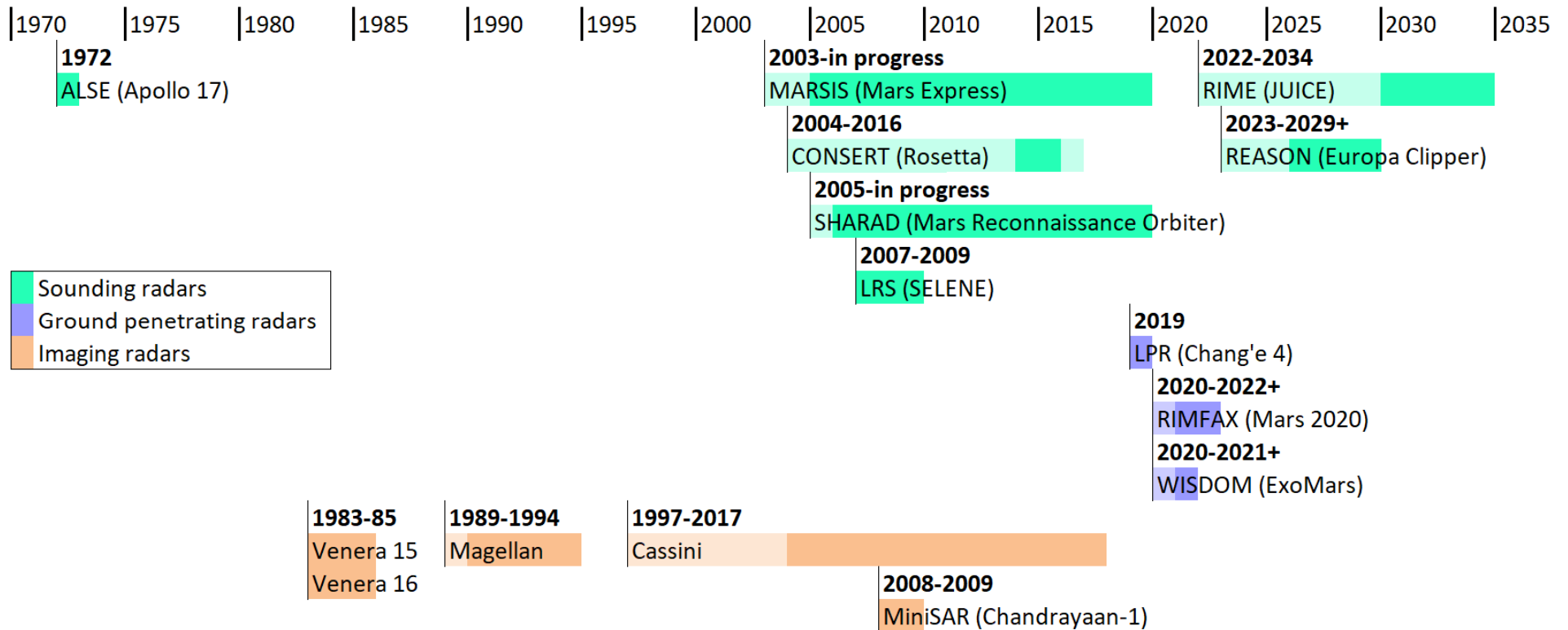
# Nadir Looking Radar



- Roughness-dependant
  - Large Roughness:  
coherence loss / limited penetration depth / no stratigraphy  
→ like altimeter signals
  - Low roughness:  
low surface scattering / reflection in the nadir direction / detection of internal reflections / vertical resolution = RF bandwidth / horizontal resolution = Fresnel zone
- Time ambiguity
  - Surface / subsurface signal
- Surface simulation
  - Ambiguity reduction
  - Data interpretation level



# Planetary radars

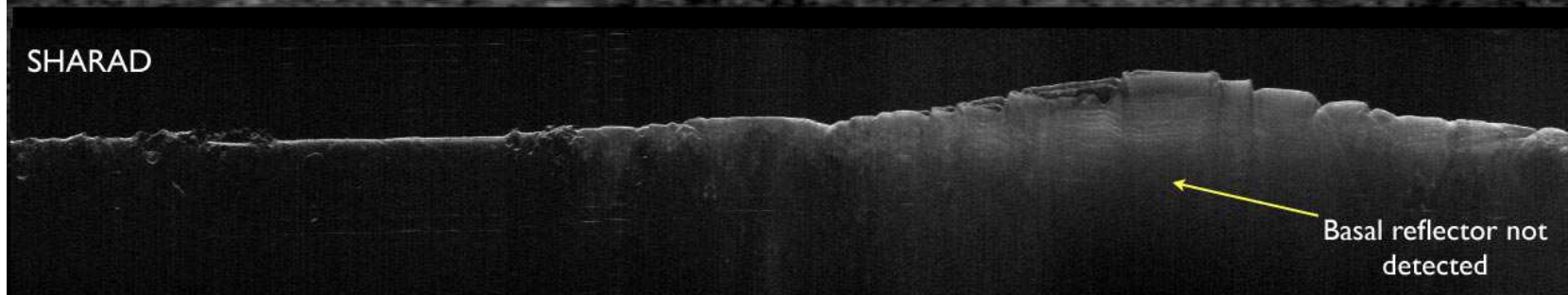
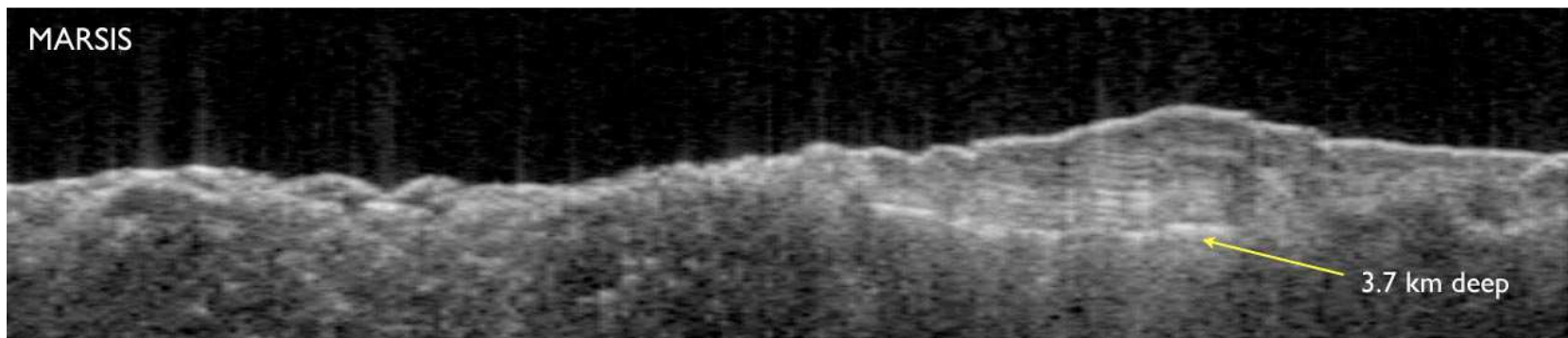
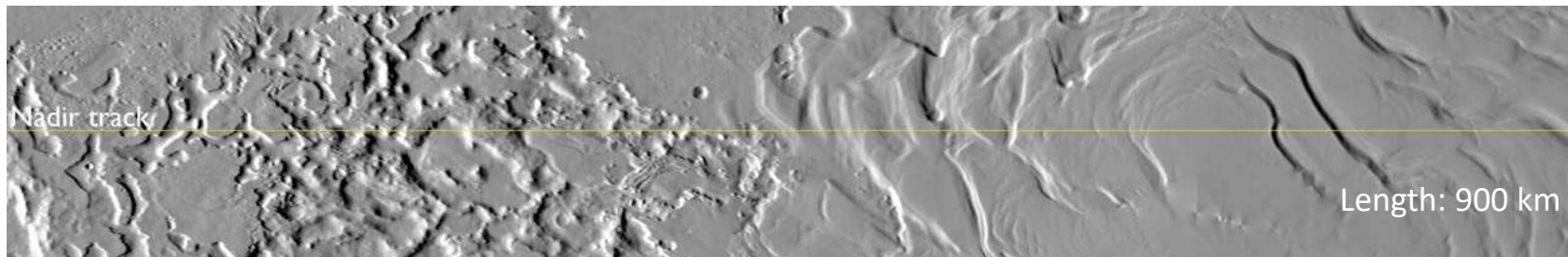


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2. A few examples & results
  - **Monostatic sounding radars on Mars & Moon**
  - Bistatic sounding radar: CONSERT on Rosetta
3. Perspectives

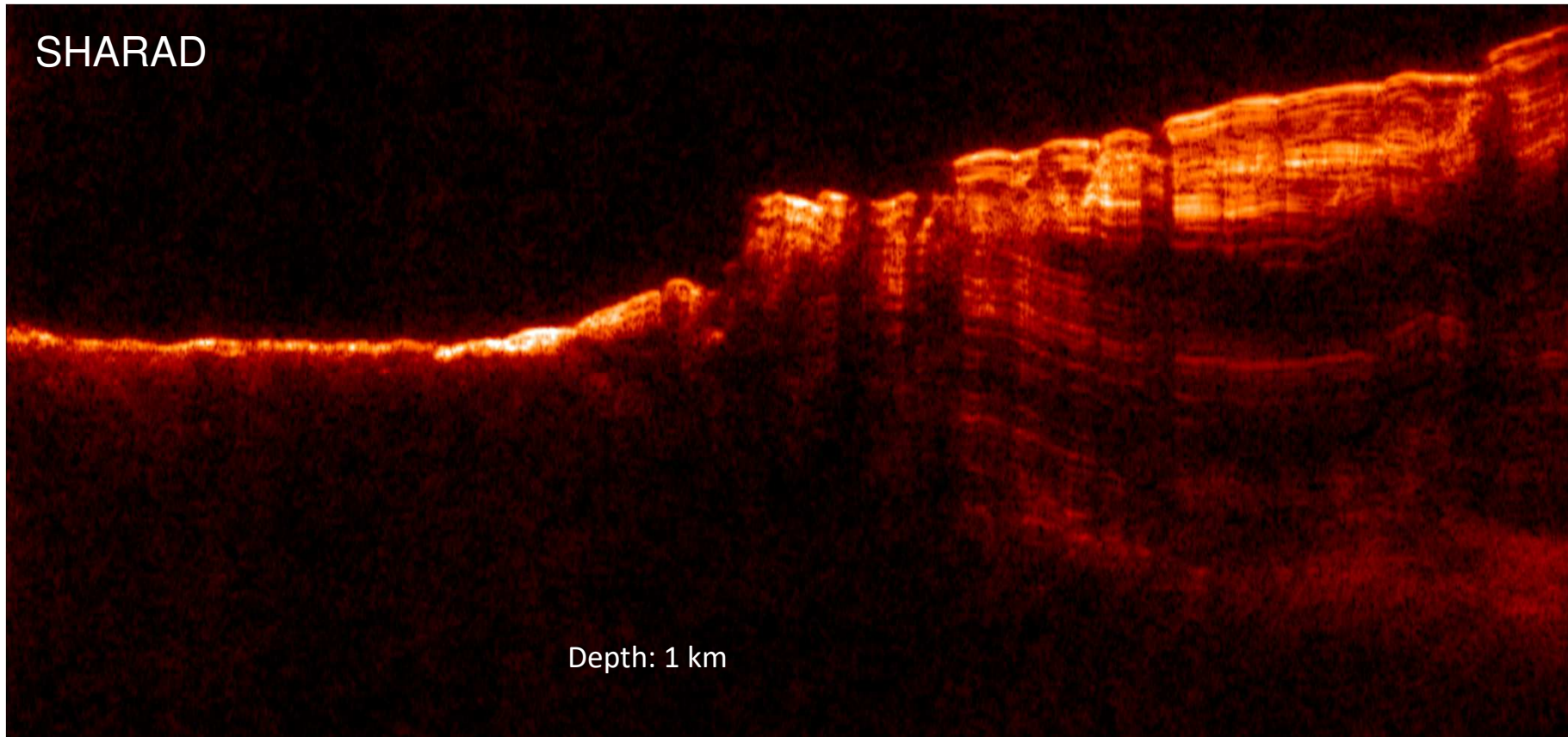
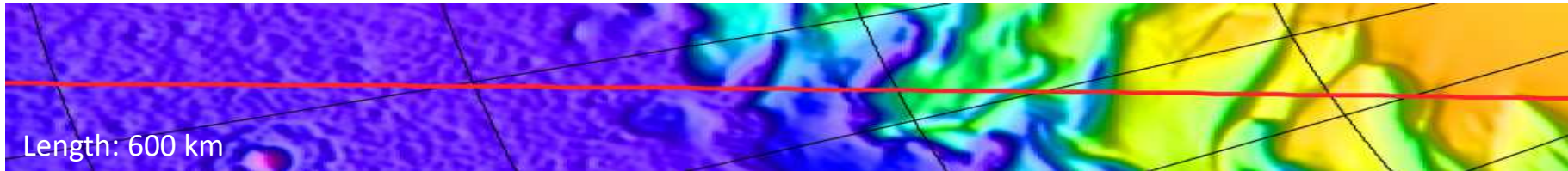
# Monostatic sounding radars on Mars

Mars South Polar cap



# Monostatic sounding radars on Mars

Mars North Polar cap

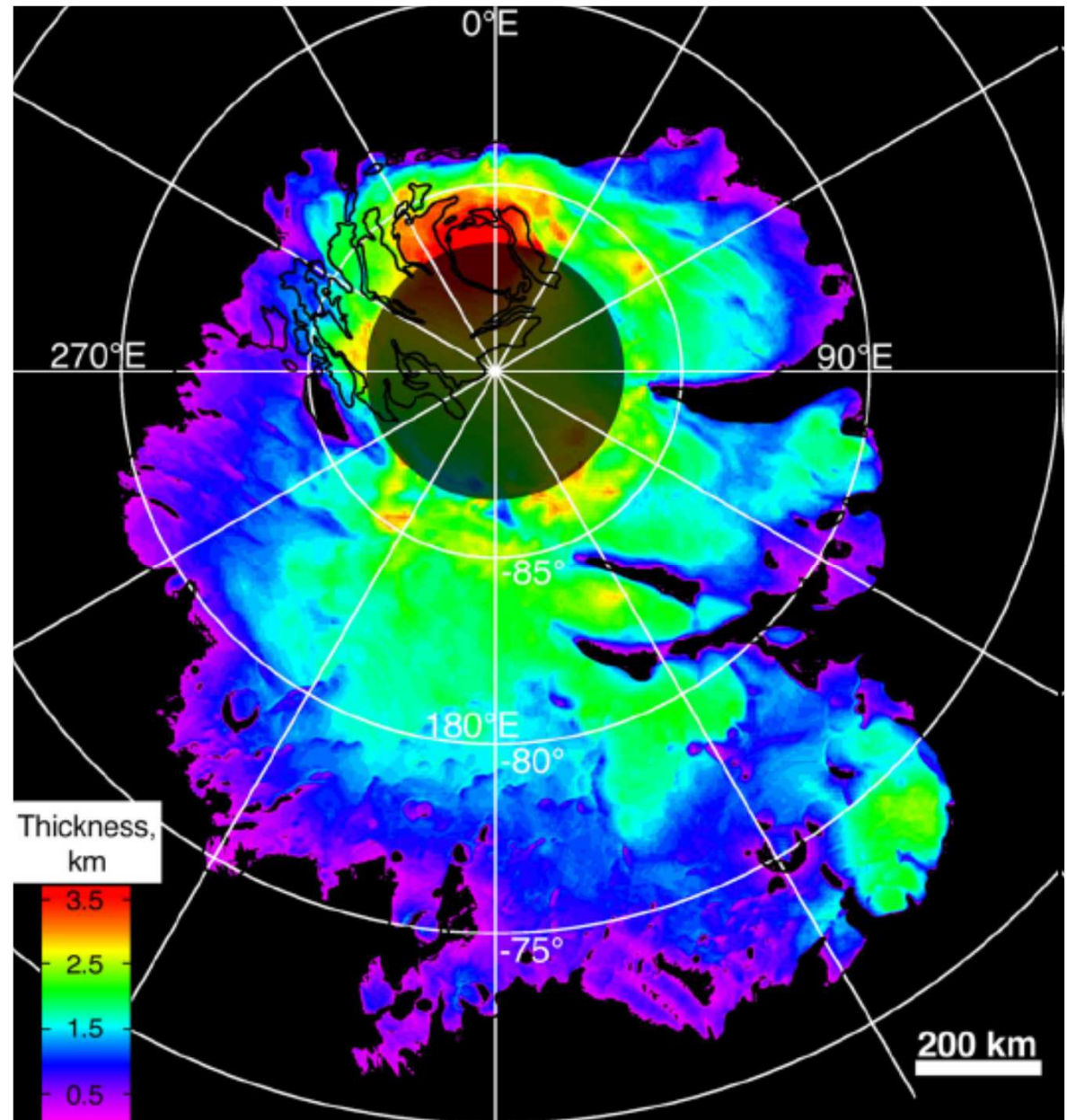




# Map of Mars South Polar Layered Deposit

Bedrock detection (MARSIS)

- Maximum thickness: 3700 m
- Volume:  $1.6 \cdot 10^6 \text{ km}^3$
- Equivalent water level: 11 m

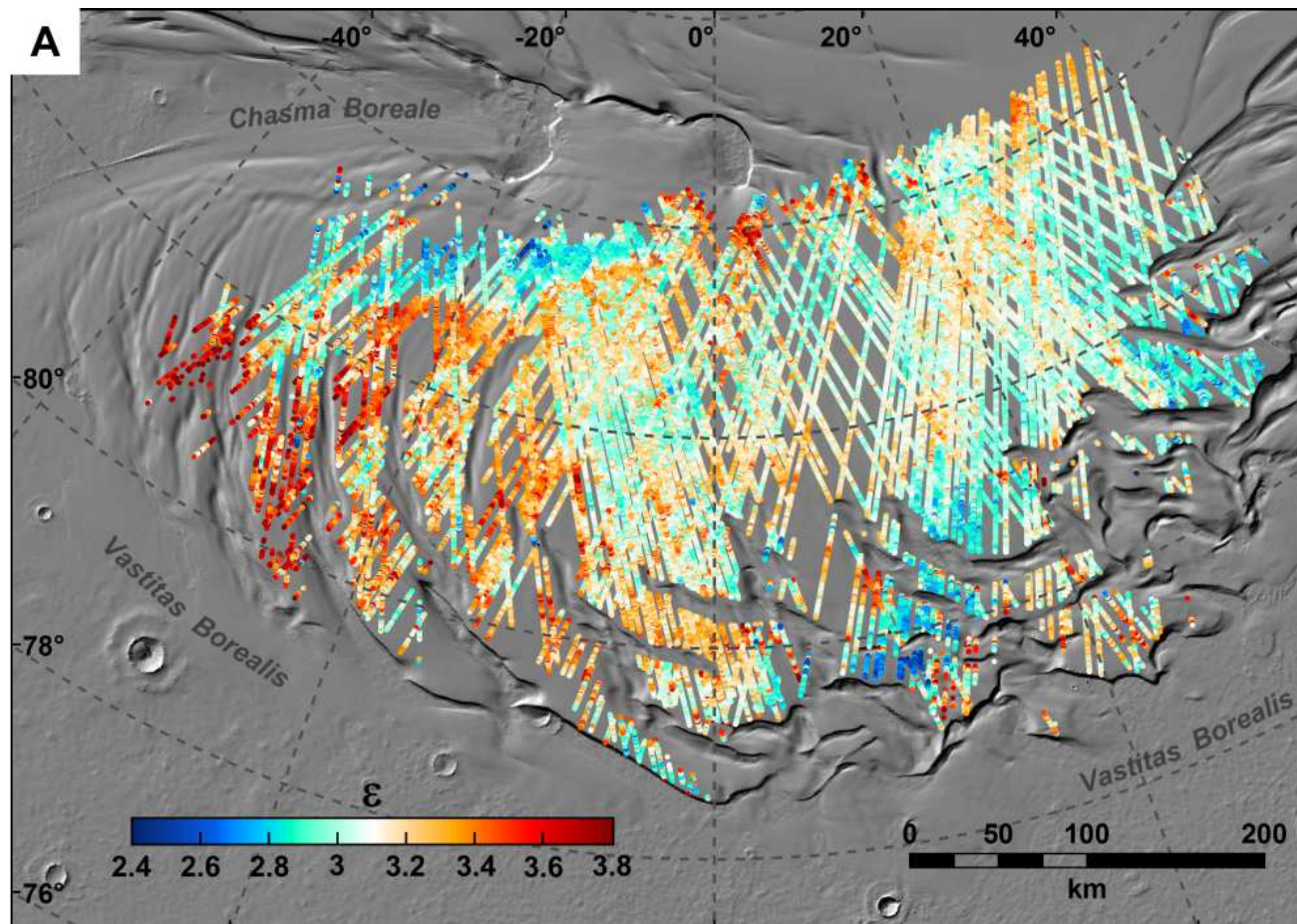


Plaut *et al.*, 2007, *Science*

# Dielectric mapping of Mars North Polar Layered Deposit with SHARAD

$$\epsilon = 3.10 \ (\sigma = 0.12)$$

$$\tan \delta \leq 0.0015 \ (\sigma = 0.0005)$$



- At Martian conditions:

$$3.0 < \epsilon < 3.2$$

impurities  $\leq 5\%$   
(Maxwell-Garnett)

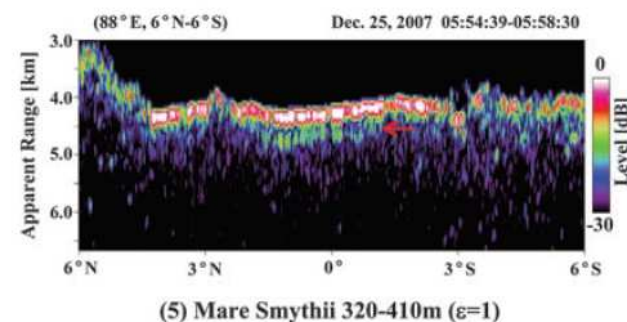
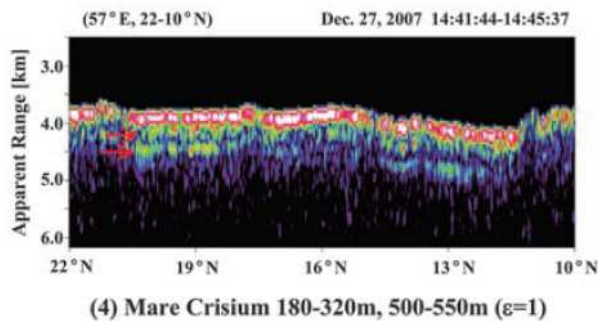
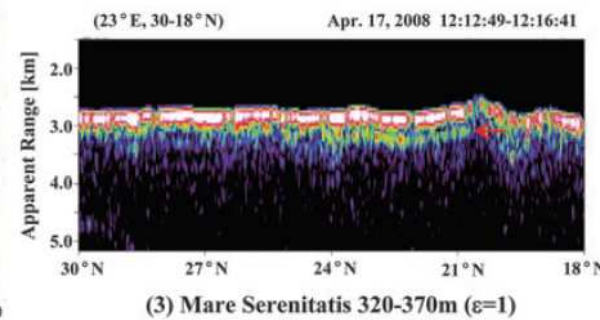
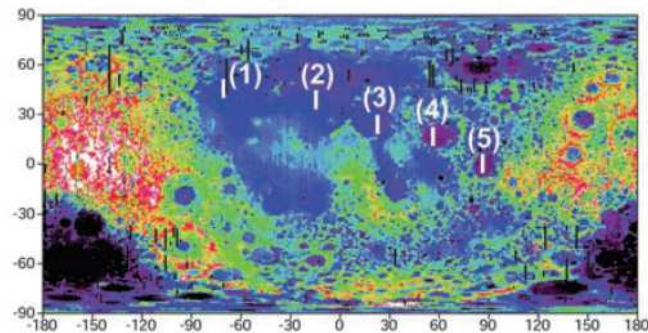
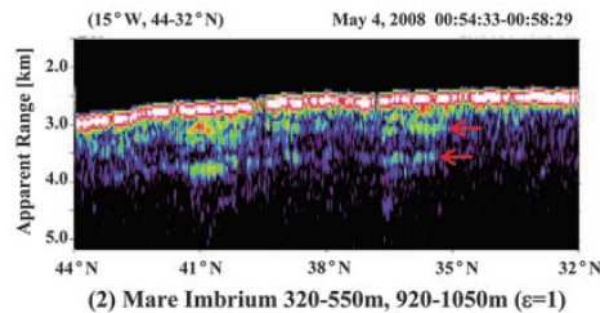
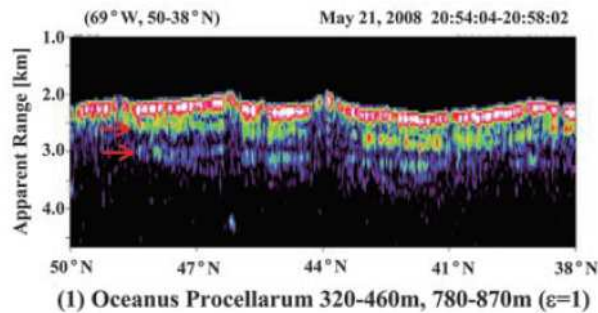
- Impurities  
concentrated at  
margins

- No signature of basal  
melting

Grima *et al.*, *GRL* 2009



# LRS observations of subsurface layers on the Moon



Subsurface geology of the Moon:

Subsurface layers at several 100s m depth under nearside maria

- Buried regolith layers

- Tectonic quiescence between 3.55 & 2.84 By

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# Tomography in transmission

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Information on average composition

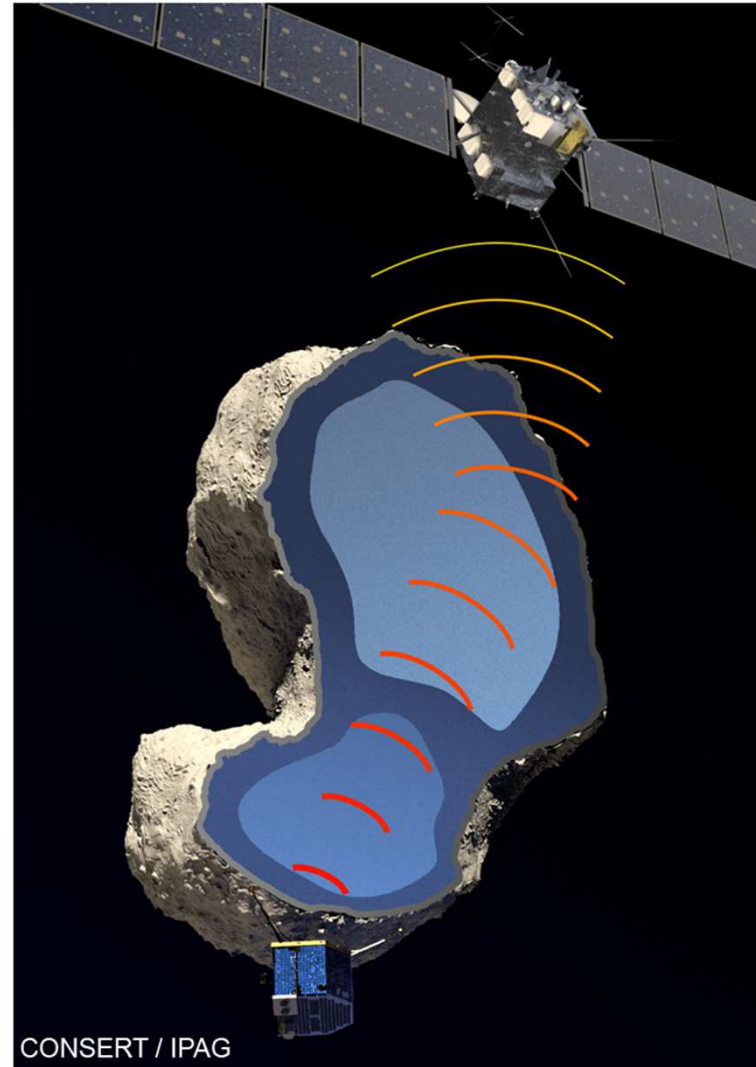
- Average Permittivity
- Absorption

Information on internal structure

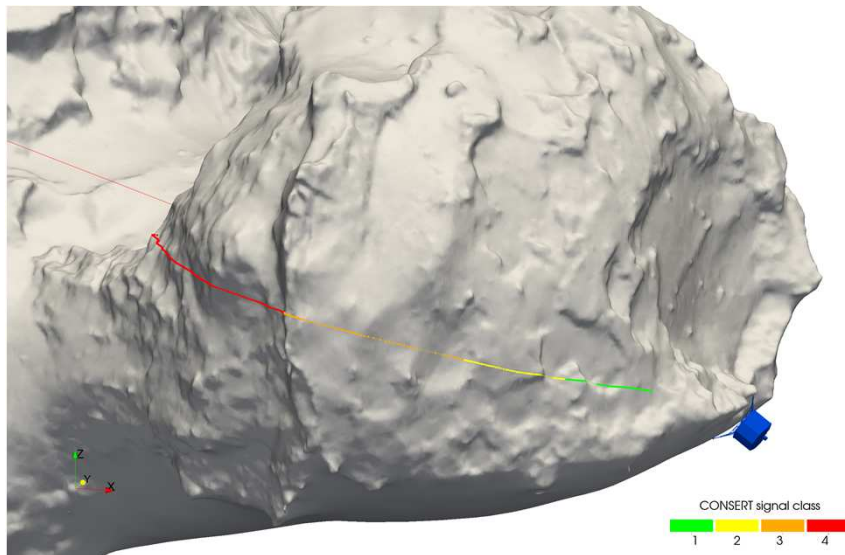
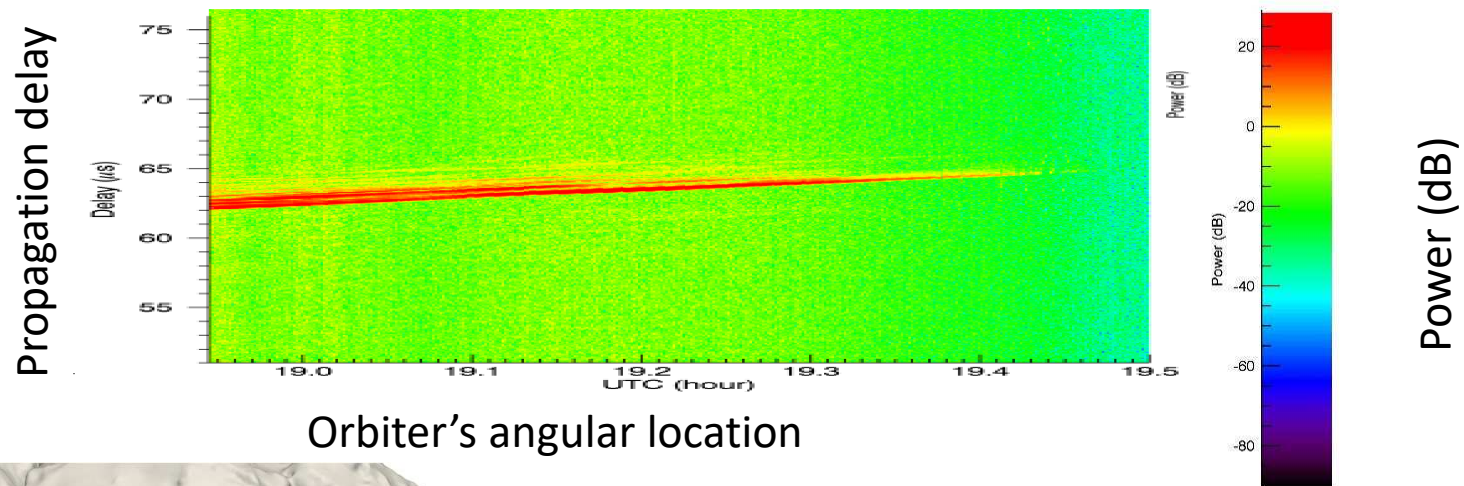
- Variation of propagation delay
- Signal scattering

Statistical tomography

- Typical size
- Typical amplitude

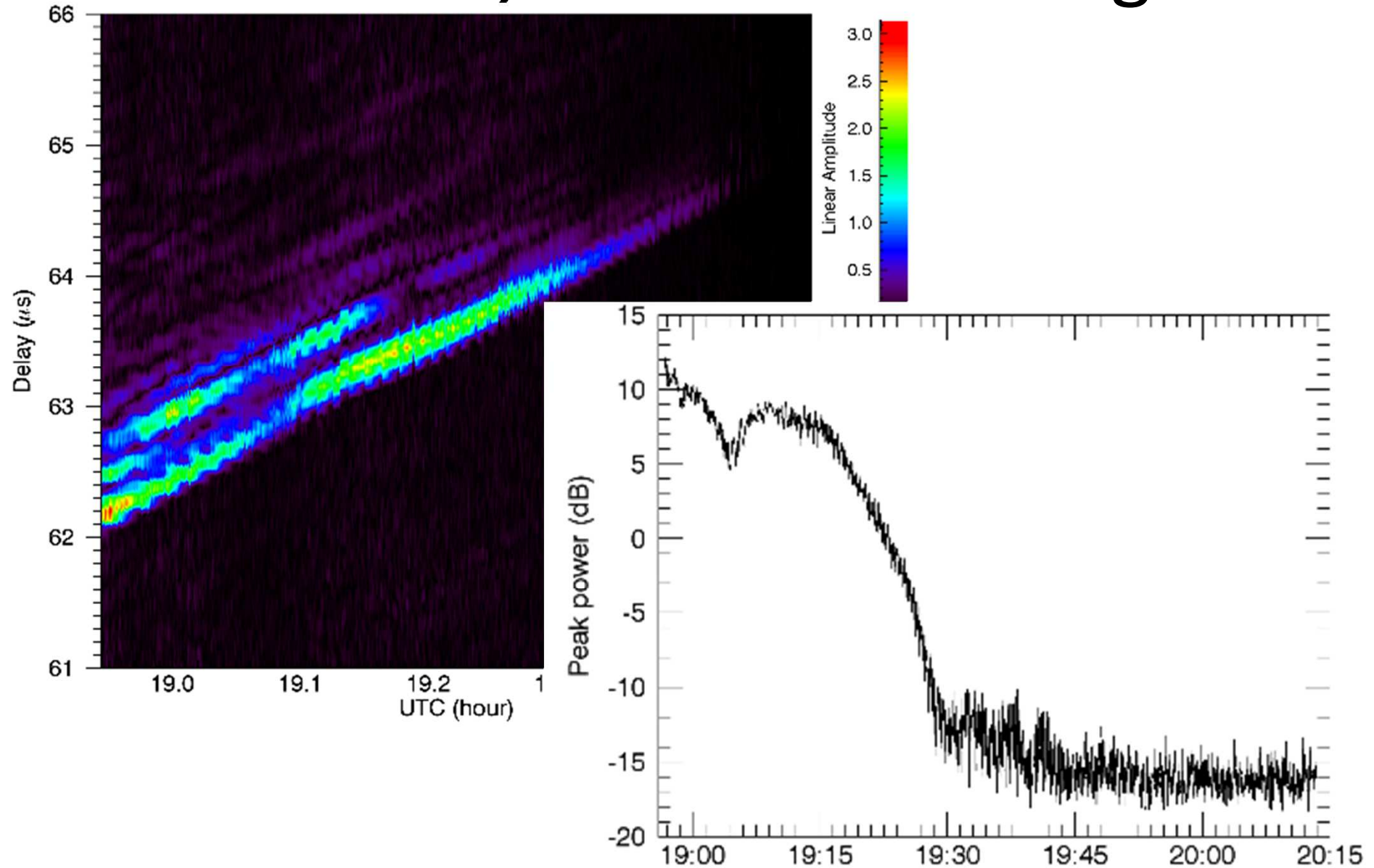


# Consert Measurement nov 14

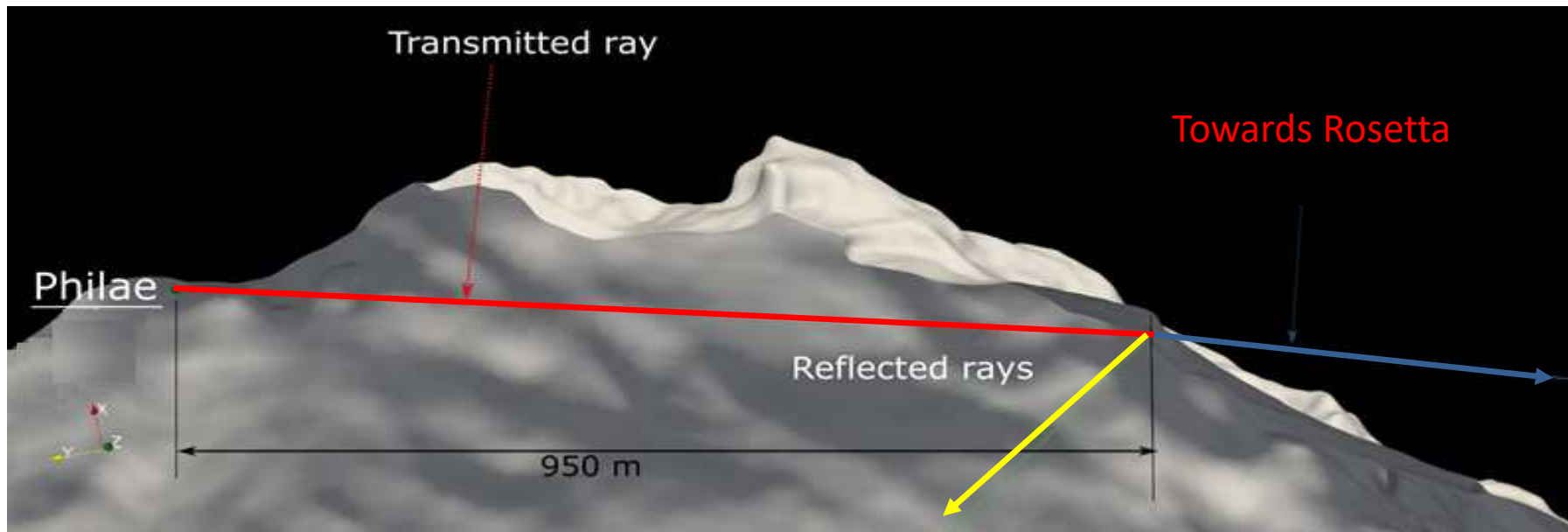


- Very limited coverage
  - No full tomography
  - Global characterization + Statistical Approach
  - Fit on direct problem

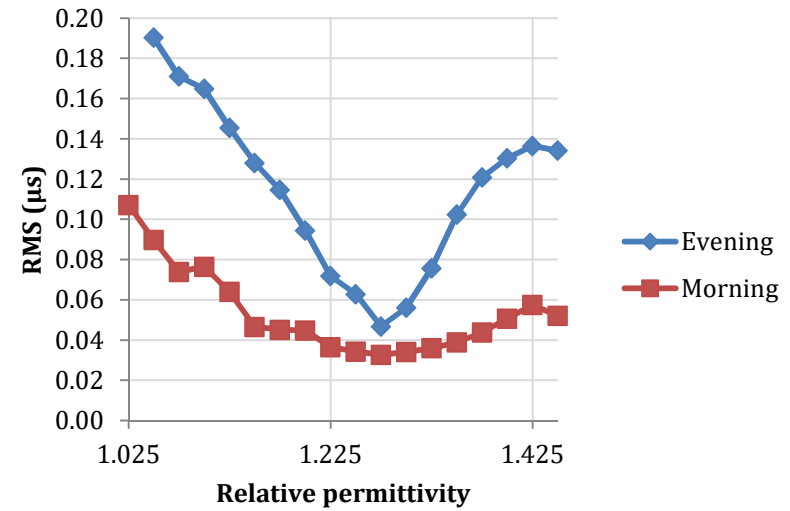
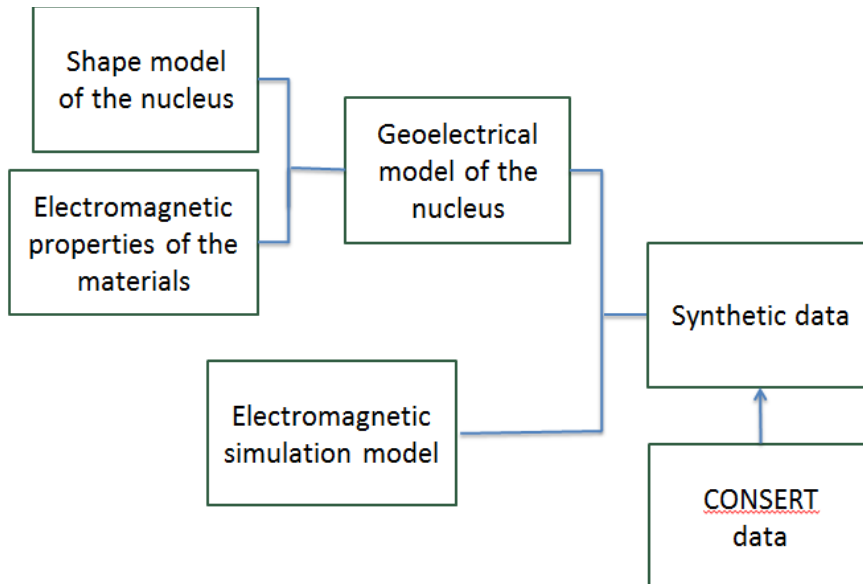
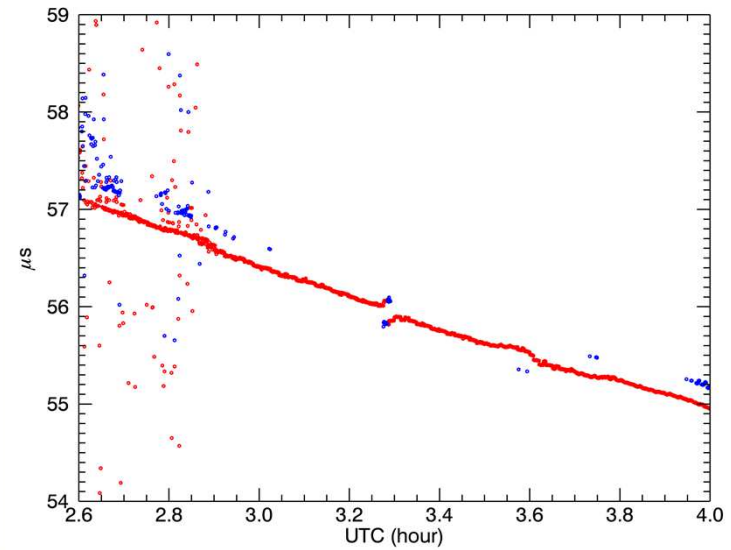
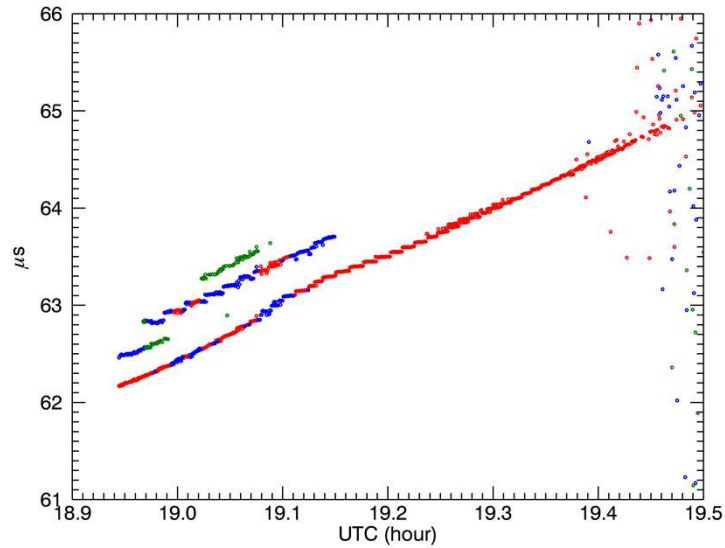
# West of Abydos – Received signals



# West of Abydos : distances inside



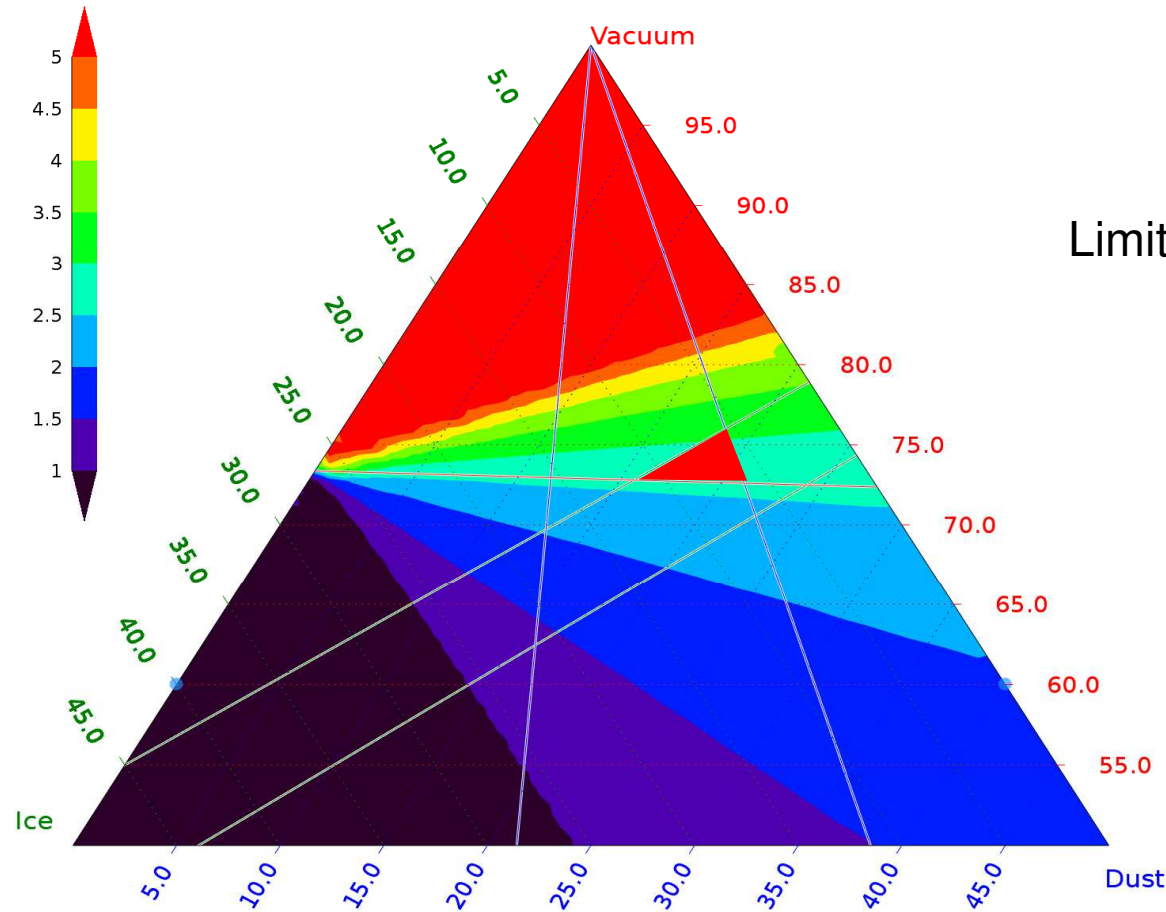
# Permittivity = $1.27 \pm 0.05$



(Kofman et al., SCIENCE 2015)

# Cosmochemical implication

## DUST PERMITTIVITY



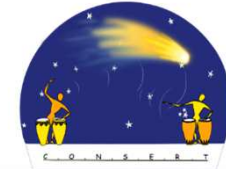
Carbon with 25% silicates  
Density = 2.3  
Permittivity = 2.6

Limited range of volume fraction  
porosity 73~82%  
ice 5 ~12 %  
dust 16 ~ 22%

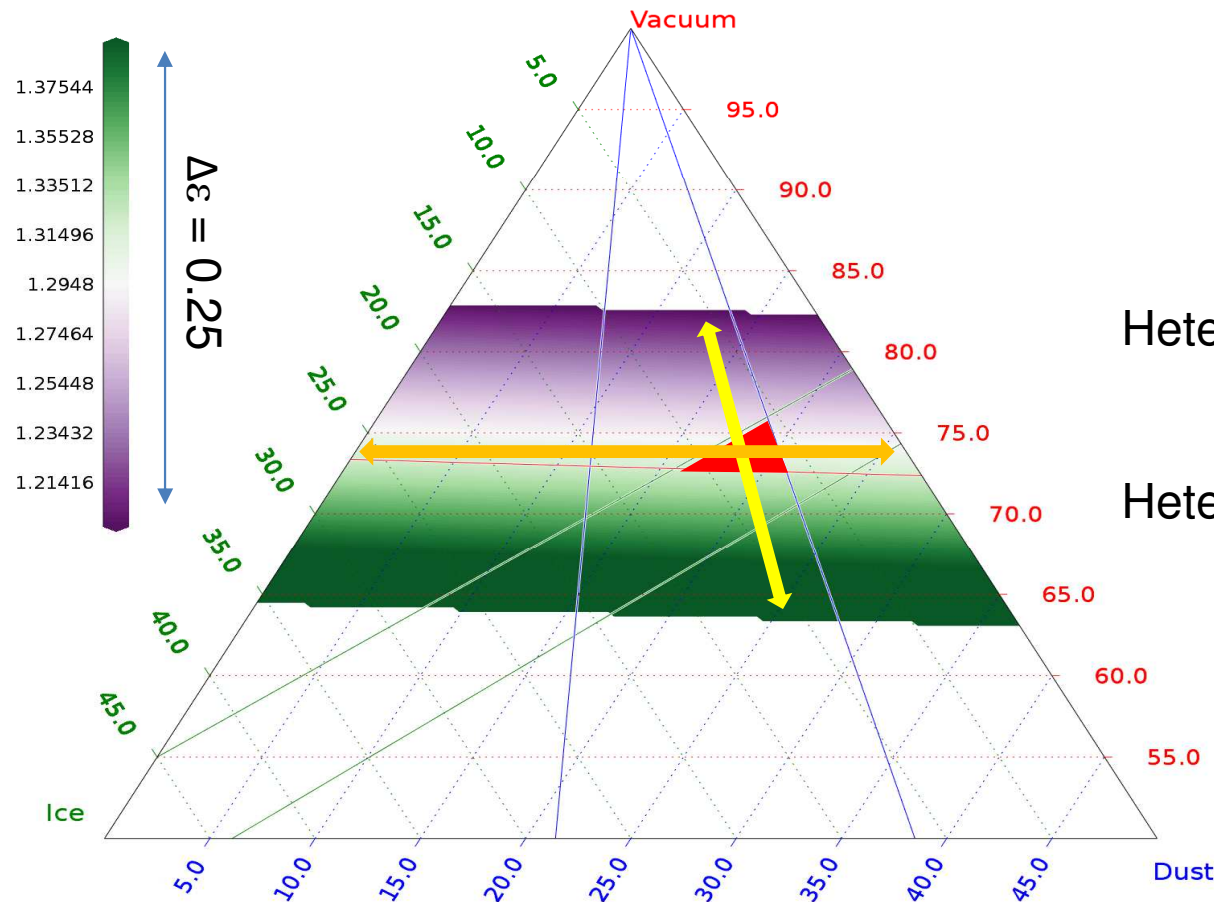
(Herique et al., MNRAS, 2016)



# How homogenous ?



## COMET PERMITTIVITY



Effective permittivity

Carbon with 25% silicates

Ice mixture

Porosity

Heterogeneity from porosity  
porosity  $\pm 10$  points

Heterogeneity from D/I  
From pure porous ice  
to dry porous dust

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  - Sounding radars for small bodies
  - Orbiting imaging radar



# Specificity of radar missions

Design very dependant on

- Medium (composition / structure)
- Acquisition geometry
- Repetition

No standard system

➔ Tradeoffs to be assessed for each mission and each body:  
medium / penetration depth / resolution

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# Internal structure of asteroids

- Sounding asteroids:

- Science

- To validate and to improve our understanding of asteroids evolution from accretion to now
    - To improve models of low gravity mechanics

- Spacecraft interactions with asteroids

- Planetary defense, Exploration, Sample return

*Characterization of heterogeneities  
from metric scale to global scale*

# MBC, Trojan and other icy bodies

- Understanding the origins of MBC, Trojan, ...
  - Space weathered surfaces
  - Pristine material covered by dry regolith
- Sounding icy bodies
  - Origins: Rocky bodies vs icy bodies
  - Accretion : Deep interior structure
  - Evolution : Surface activation processes, layers

# Internal structure : How ?

*The radar is the instrument to characterize the interior from metric scale to global scale*

- **Deep Interior Radar : LFR / AIM**

A Low Frequency Radar to perform the tomography of the deep interior (structure, size of block and compositional heterogeneity)

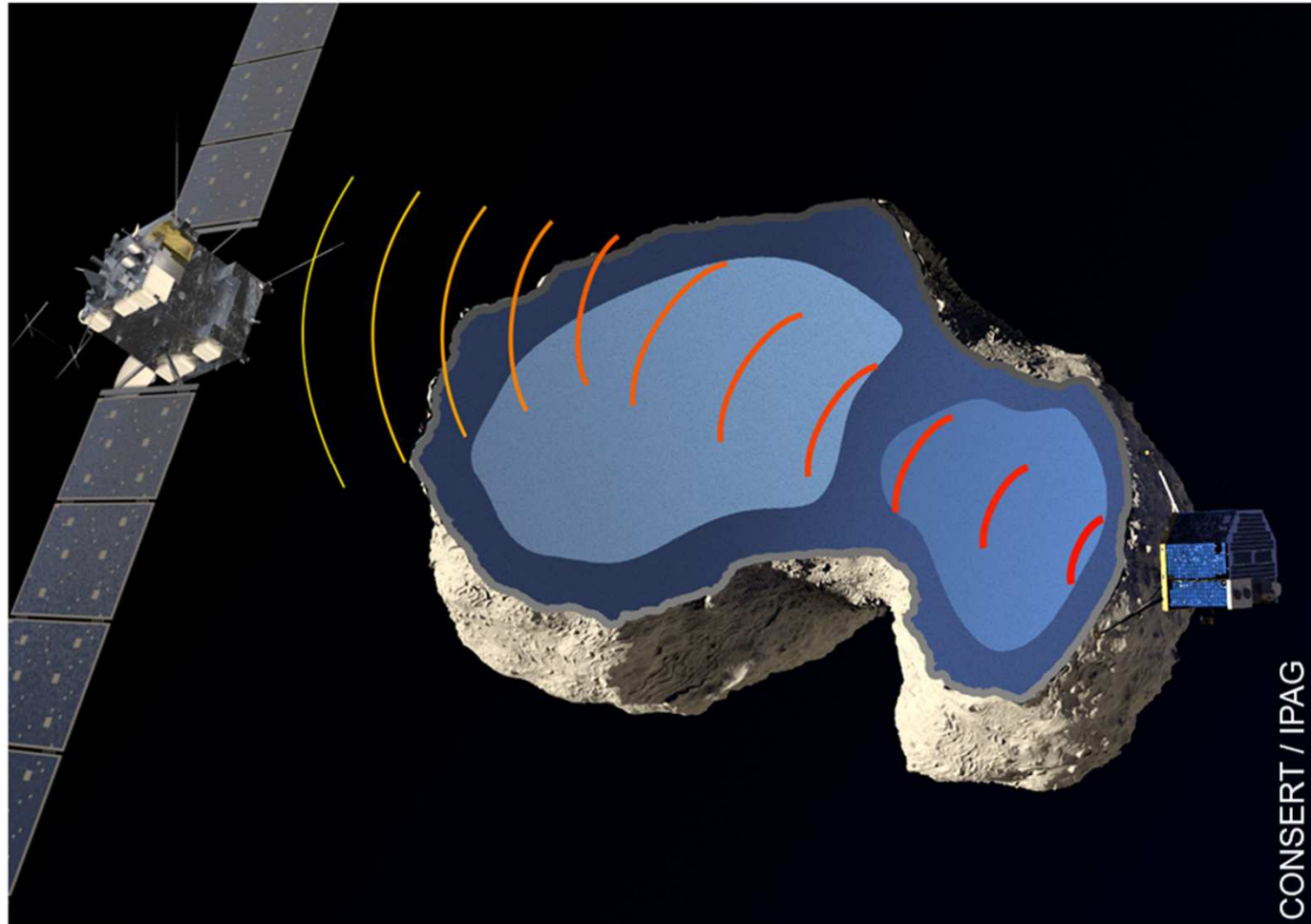
→ Bistatic radar (Consert-like) with Mascot 2 on Didymoon, or Cubesat

- **Shallow Subsurface Radar : HFR / AIM**

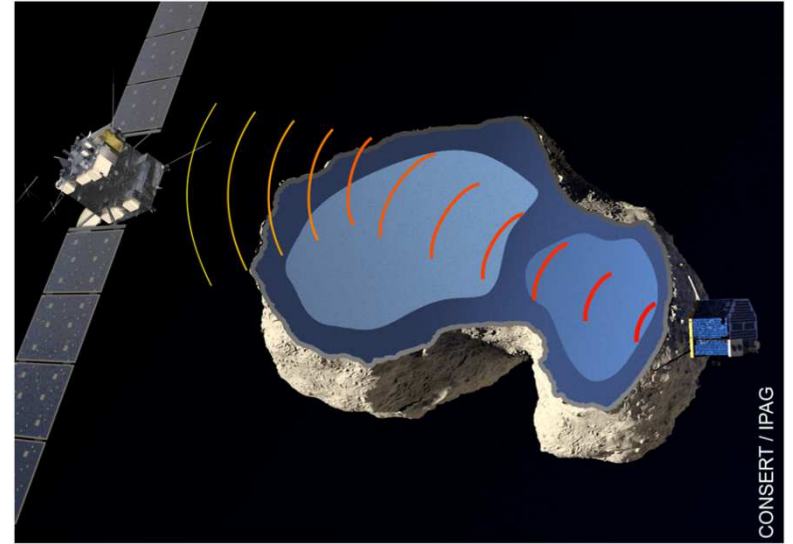
A Higher Frequency Radar channel to fathom the regolith (depth and structure)

*(Herique, ASR, 2017)*

# LFR : concept

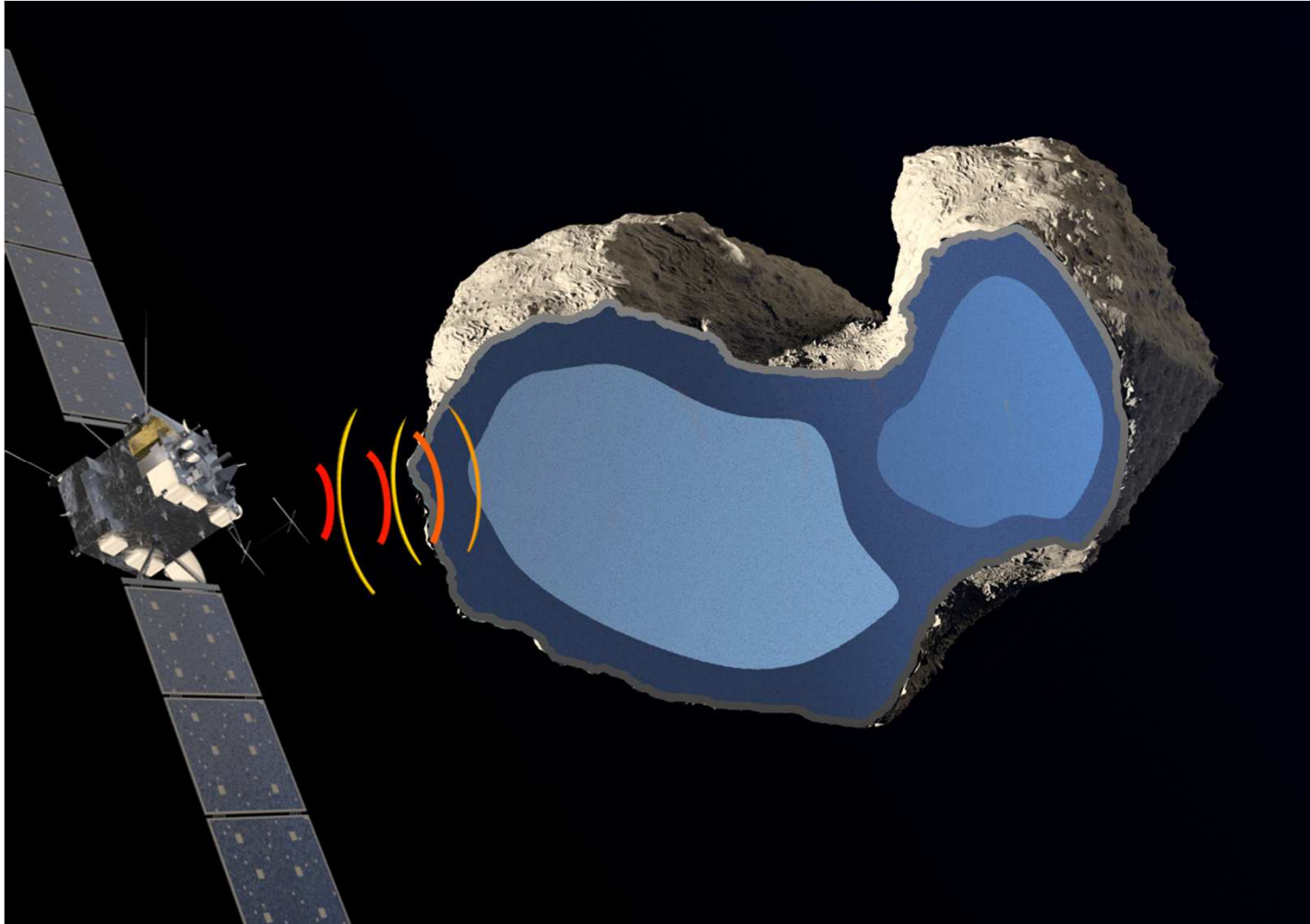


# LFR : Objectives



- **Global characterisation (one orbit)**  
Average permittivity → composition & porosity  
Average heterogeneity (few metres) → local variation  
Spatial variation of these average parameters (1 to a few orbits)  
Large structures & stratifications
- **Tomography (numerous orbits)**  
3D Tomography of the interior
- **Secondary objectives**  
Gravimetry & dynamic state (direct link Lander / Orbiter)

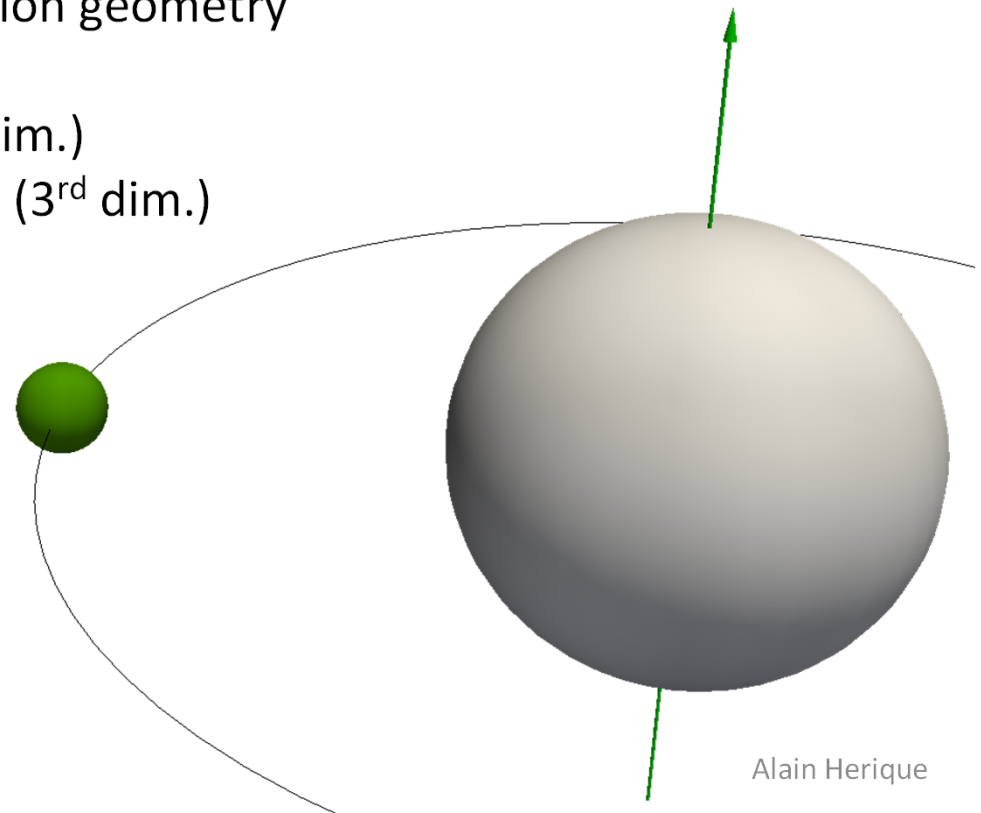
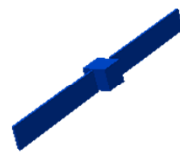
# HFR : concept





# HFR : Tomographic SAR

- Synthetic Aperture Radar 400 MHz - 3 GHz
- Mapping of the backscattering coefficient (power)
- Penetration depth: first tens of meters
  
- Performances given by the acquisition geometry
  - range measurement (1<sup>st</sup> dim.)
  - Didymoon / Didymos motion (2<sup>nd</sup> dim.)
  - S/C motion : multipass acquisitions (3<sup>rd</sup> dim.)



Alain Herique

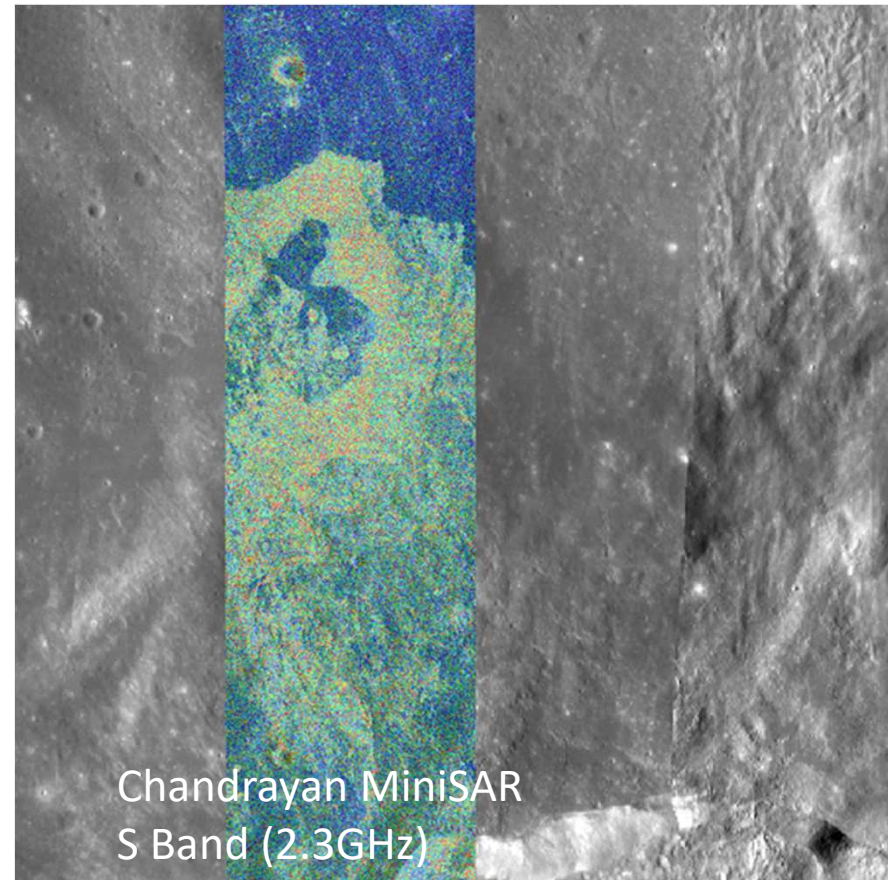
# HFR : regolith

1 pass

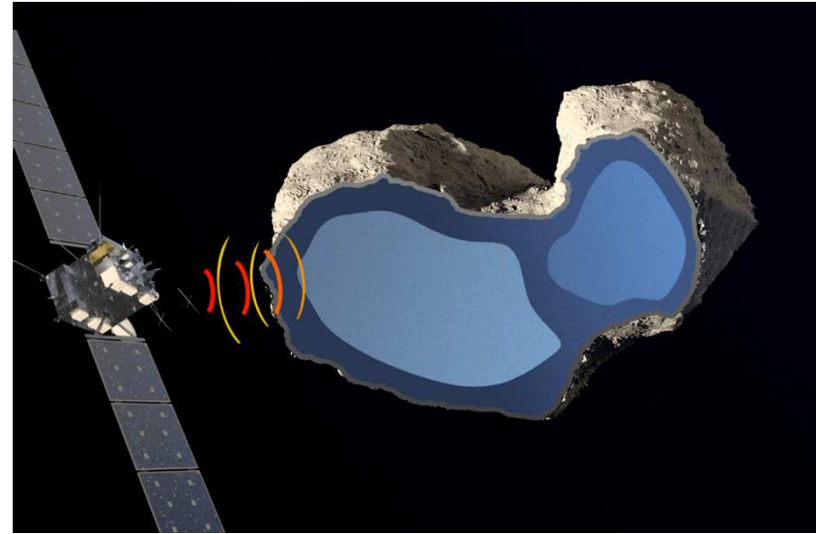
- 2D mapping
- including surface and subsurface
- 2 Polarizations

~20 passes

- 3D tomography
- Resolution  $\sim 1$  m
- Sensitivity  $-40 \text{ dB.m}^2/\text{m}^2$
- Dynamic range  $-20 \text{ dB}$



# HFR : Objectives

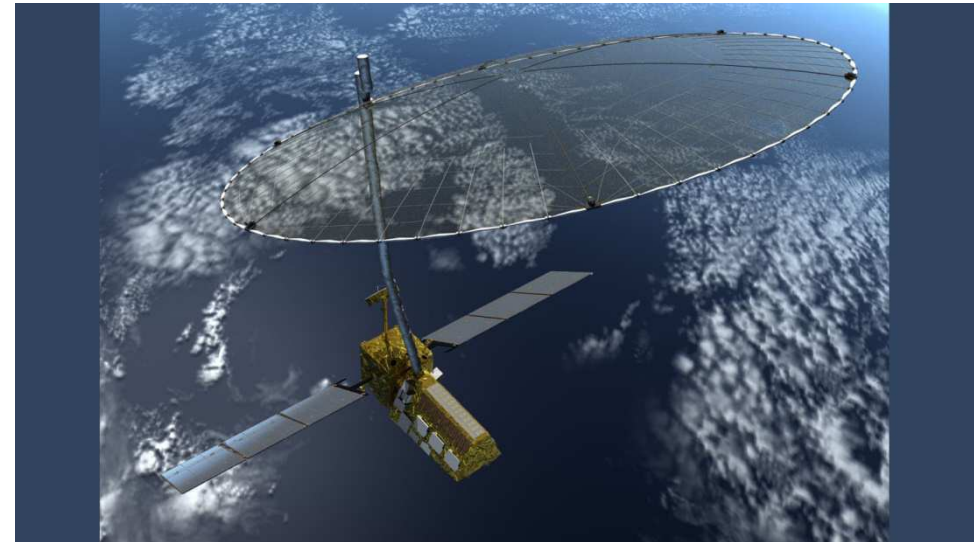
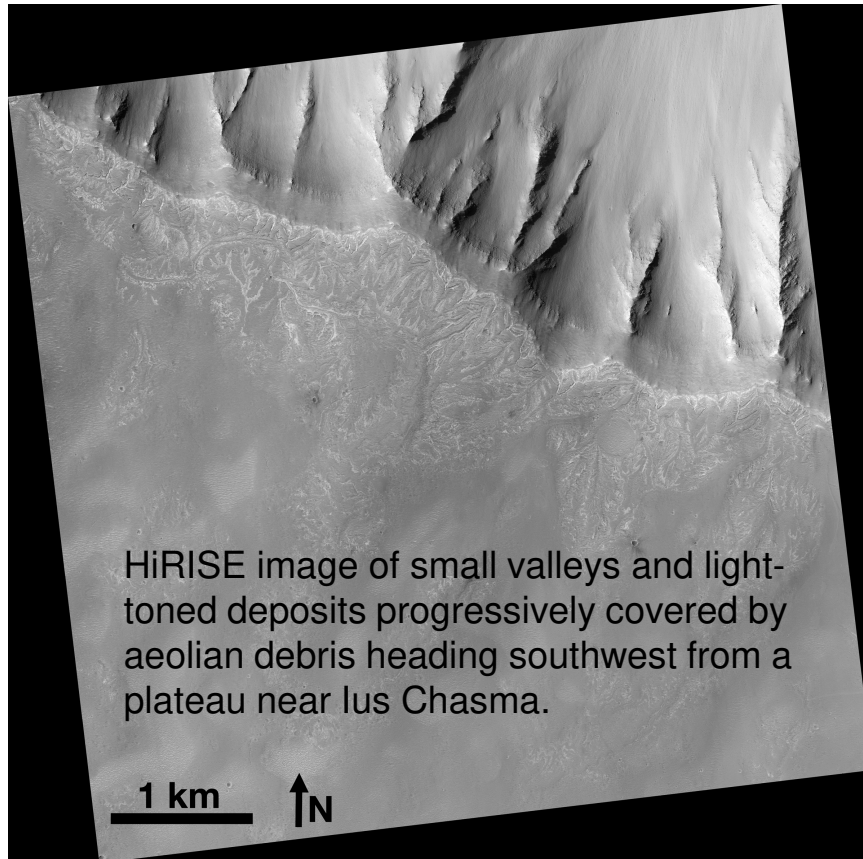


- **2D Cartography (one orbit)**  
**3D Tomography ( 20 acquisitions)**  
Detection of structures close to the surface (20 m in rocks → 100 m in ices)  
Stratigraphy, cavities, structures linked to activity  
Regolith diversity, stratigraphic connection of units
- **Interferometry**  
Shape model (vertical resolution  $\sim \lambda / 10$ )  
Temporal evolution (re-deposition, mobility)
- **Secondary objectives**  
Gravimetry & dynamic state (direct link Orbiter/surface)

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  - Sounding radars for small bodies
  - **Orbital imaging radar**

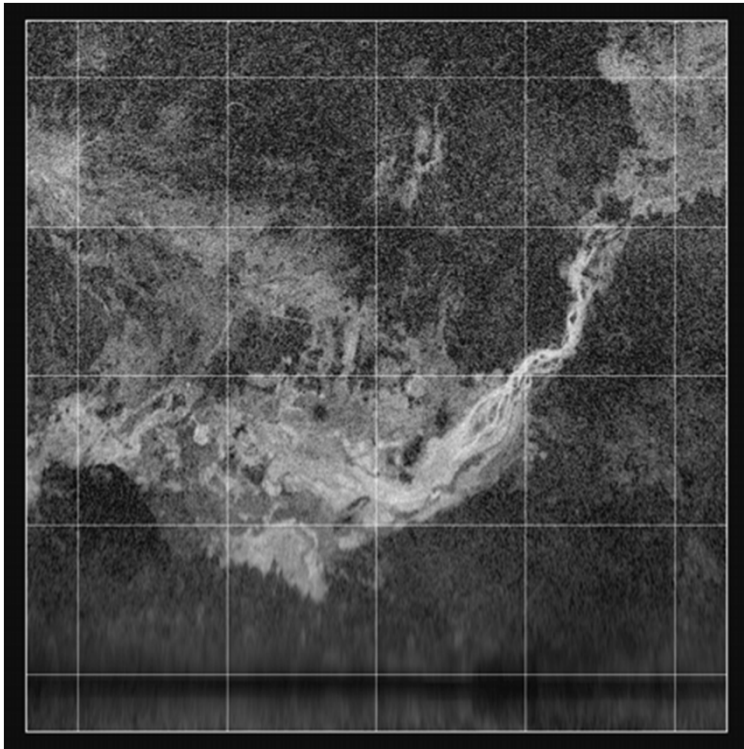
# Orbital Radar for Mars



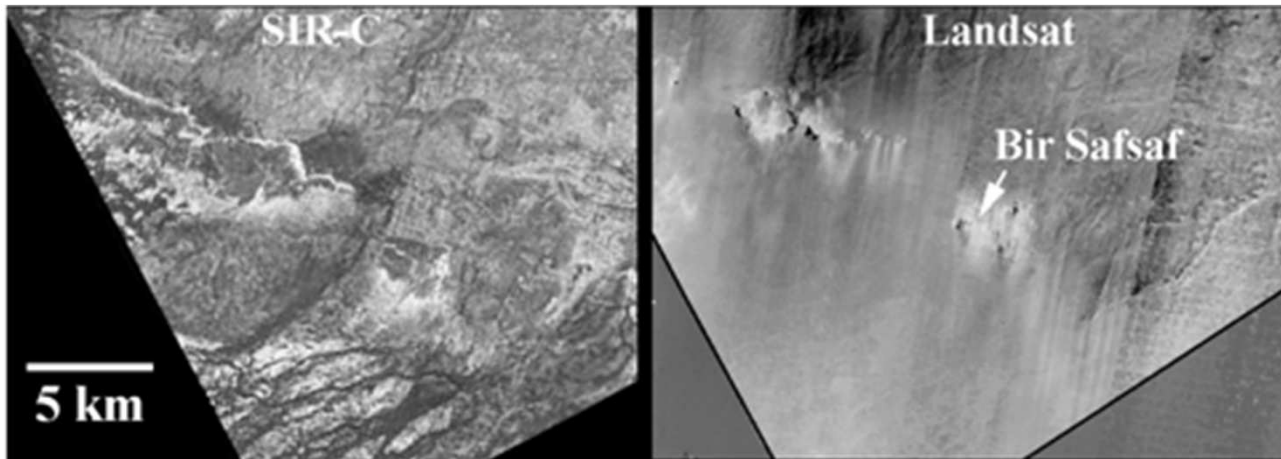
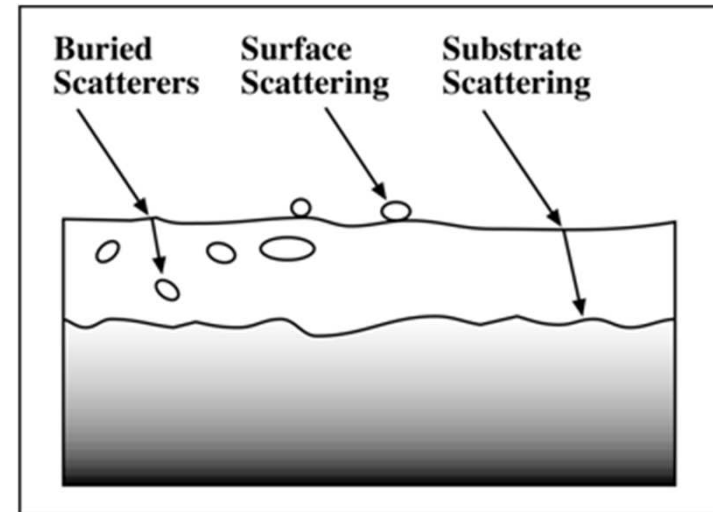
Deployable mesh antenna makes long-wavelength SAR possible for Mars

- The shallow subsurface of Mars contains clues to geologic and climate processes that cannot be fully understood through VIS-IR images, no matter how fine their resolution.
- These clues are recorded by:
  - The morphology of bedrock and the occurrence of ice lenses beneath layers of fine material.
  - The physical character (rock abundance and loss properties) of deep regolith or mantling layers.
  - The detailed layering and spatial variability in dust loading of the polar caps.
- Imaging radar at 30-60 cm wavelength, with penetration measured in meters and sensitivity to decimeter-scale roughness and rocks, is the ideal tool for characterizing the near-surface environment on a global scale.

# Mapping The Hidden Past - Buried Bedrock



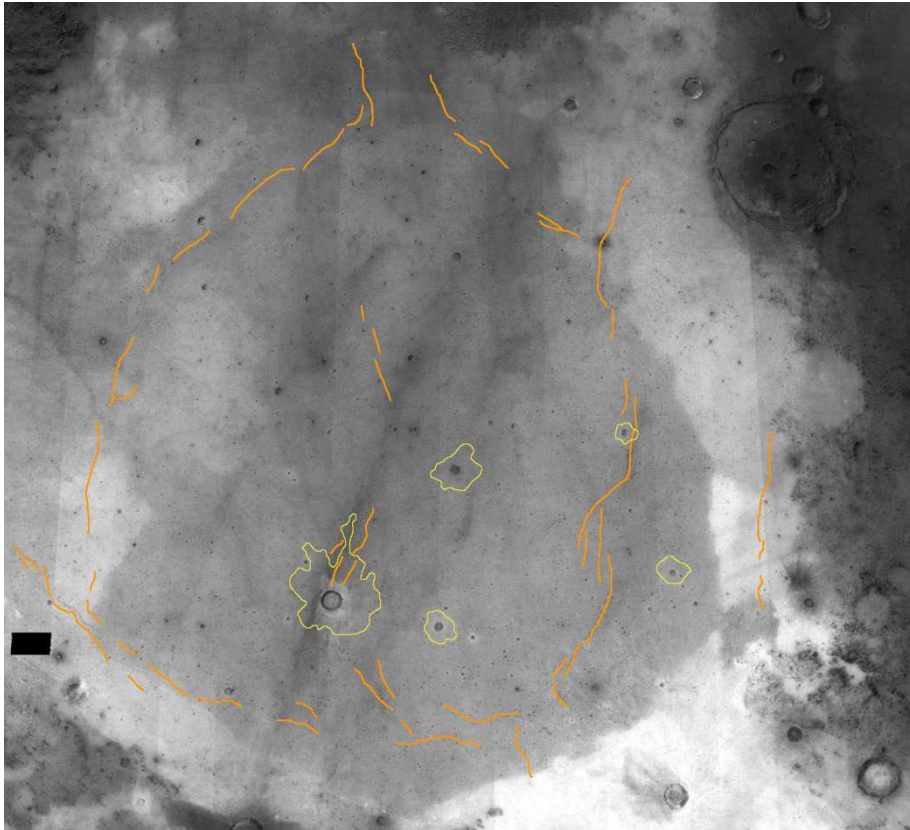
Earth-based 13-cm imaging radar showing bright echoes from lava flows in Elysium Planitia buried by 2 m or more of debris (Harmon and Nolan, 2007).



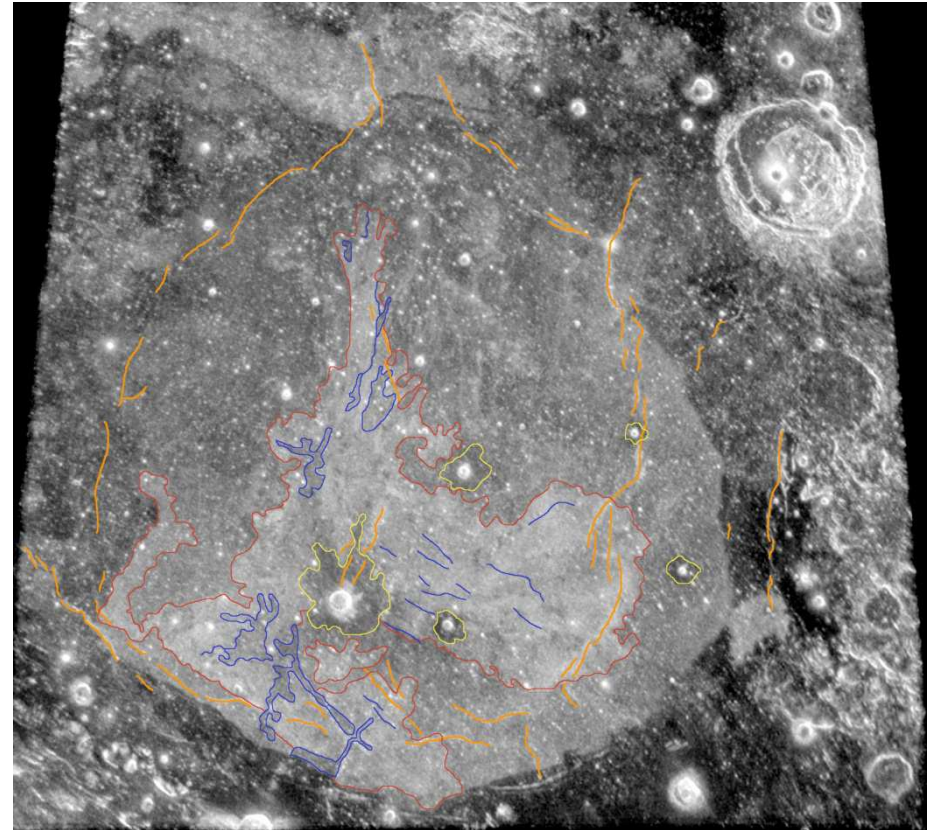
The “radar rivers” of the Sahara, detected due to differences in scattering from buried rough bedrock and sand-filled channels.



# An Example from the Moon



Clementine UV-VIS derived map of  $\text{TiO}_2$  content in Serenitatis mare units.

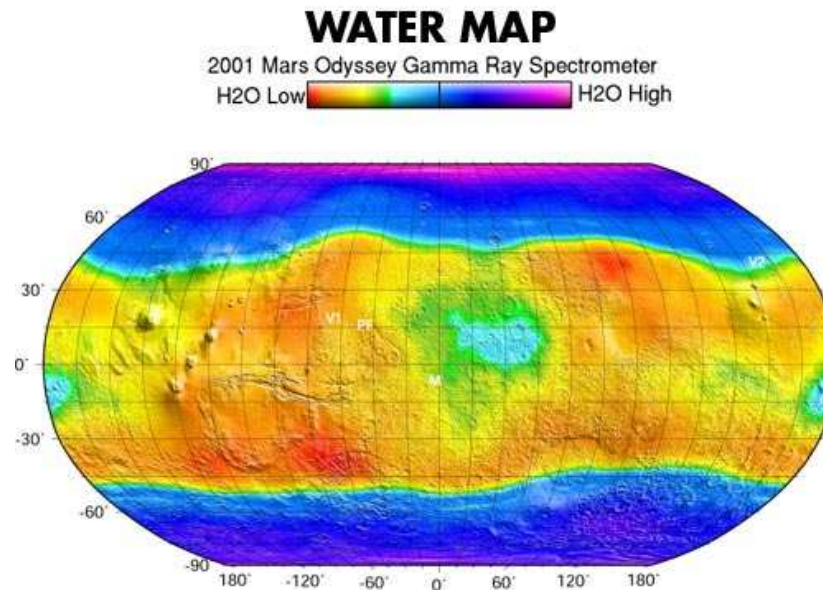
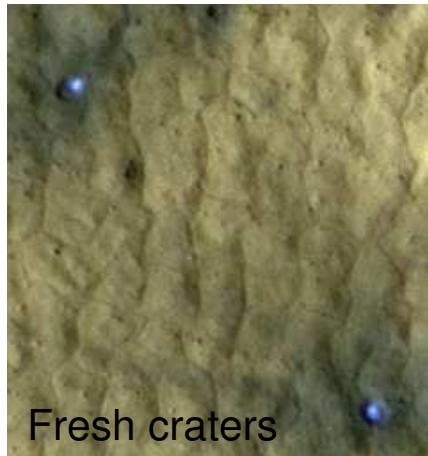


70-cm wavelength radar backscatter image of Mare Serenitatis.

Rugged plates or rubble at the base of the lunar regolith help to reveal very subtle changes in the chemistry of the overlying basalts - unseen flow patterns emerge.

Similar data for Mars will unveil vast areas mantled by meters of dust.

# Shallow Ground Ice



- Ground ice clearly exists near the surface across much of the high-latitude region.
- Radar echoes from “clean” ice layers will very different than from deep weathered soil.
  - Clean ice with cracks can be exceptionally radar-bright.
  - Requires ice to be thick with respect to wavelength (1-3 m)
  - Circular polarization ratio a better discriminator of thick ice at longer wavelengths, where small rocks do not dominate the diffuse radar return.

